

Bandits: Thompson Sampling and Contextual Bandits

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**CS/Stat 184(0): Introduction to Reinforcement Learning
Fall 2024**

Today

- Feedback from last lecture
- Recap
- Thompson sampling
- Contextual bandits

Feedback from feedback forms

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1. Thank you to everyone who filled out the forms!

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2. Green can be hard to see

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Without the Bernoulli assumption, we may need many more dimensions to describe the possible distributions, and hence have to define a much higher-dimensional prior

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What changes with t is our **information** about μ , i.e., the posterior distribution, as we collect more and more data by pulling arms via a bandit algorithm

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π can often be chosen “uninformatively” to a default prior such as the uniform, or can encode nuanced prior information/belief about the arms' reward distributions

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Although derived from the Bayesian bandit, Thompson sampling has excellent practical performance across bandit problems, whether or not they are Bayesian!

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$$\liminf_{T \rightarrow \infty} \frac{\mathbb{E}[N_T^{(k)}]}{\ln(T)} \geq \frac{1}{d(\nu^{(k^*)}, \nu^{(k)})},$$

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Thompson sampling doesn't know this, and neither does UCB (although UCB wouldn't happen to make the same mistake in this case).

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Such tuning can improve Thompson sampling's performance even for reasonably large T (the asymptotic optimality of vanilla TS is *very* asymptotic)

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Algorithm/proof beyond scope of this class, but rely on an efficient approximation to the Gittins index via **dynamic programming** that updates when an arm is pulled

Exactly optimality in Bayesian Bernoulli bandit

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Performance is great, even if prior is wrong, but algorithmic principle behind it **brittle**: doesn't easily extend to exact optimality in even slightly more complex settings

Today

- ✓ • Feedback from last lecture
- ✓ • Recap
- ✓ • Thompson sampling
- ✓ *AA* • Contextual bandits

Beyond simple bandits

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Which user comes in next is random, but we have some **context** to tell situations apart and hence learn **different optimal actions**

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Context at time t encoded into a variable x_t that we see **before** choosing our action

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π^\star is the policy we compare to in computing **regret**

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π_t might seem unfamiliar since we haven't talked about a **policy** in bandits before, but actually we've always had it, it's just that without context, we didn't need a name or notation for it because it was so simple!

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Still know posterior over $k^\star(x_t)$ that can draw from to choose a_t ; this is $\pi_t(x_t)$

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Not *identical* readership, but still both on NYT, so probably still *similar* readership!

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Choosing the best model, fitting it, and quantifying uncertainty are really questions of supervised learning

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Summary:

- Thompson sampling **samples** optimal arm from its (posterior) distribution
- Thompson sampling achieves **excellent performance** in practice
- Contextual bandits adds **state** to bandit problem, but algorithms extend
- For better performance, need modeling via **supervised learning**

Attendance:

bit.ly/3RcTC9T



Feedback:

bit.ly/3RHtlxy

